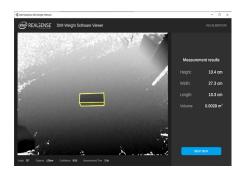
Intel® RealSense™ Dimensional Weight Software

## Measuring Packages At the Speed of Light

Intel® RealSense™ Dimensional Weight Software (DWS) is an easy to use, high-speed, precise volumetric measurement software solution.



## All-in-One SDK Solution

By combining the power of our proprietary volumetric measurement SDK with the award-winning Intel RealSense LiDAR Camera L515, Intel Realsense have built a legal for trade ready highly accurate measurement platform. From small boxes to large pallets, our solution enables logistics companies to better manage their inventory and shipments. Intel® RealSense™ DWS enhances billing accuracy, aids in warehouse space management, and increases workflow efficiencies through fast and accurate to-the-millimeter measurements. Our platform seamlessly integrates with existing enterprise systems or can be activated right out of the box.

## **Highest Accuracy**

DWS is designed with the highest accuracy for logistic companies and companies who are building volumetric measurement systems. From small boxes to pallet sizing, legal for trade billing or warehouse space management systems, DWS and RealSense L515 LiDAR Camera enable it all!

## **Seamless Integration**

Start evaluating today with the DWS Viewer app and test your setup. DWS Viewer enables easy integration of the L515 LiDAR camera and the DWS library without any need for development. Just connect the camera to your PC and run the application – no installation needed!

Operational Mode* Fixed/ Latency 2 seco Camera Position Top and Measurement objects Cuboic Range 0.8m t Measurement accuracy at Range (A)† 0.8-1.5 Measurement accuracy at Range (B)† 0.8-2.5	rs - based on the Intel RealSense LiDAR Camera L515  Static. Moving/Mobile coming soon  nds  Id side view (90° to 45° relative to the top plane of the box)  ds. Irregular objects coming soon.  o 4m**
Latency 2 seco Camera Position Top an Measurement objects Cuboic Range 0.8m t Measurement accuracy at Range (A)† 0.8-1.5 Measurement accuracy at Range (B)† 0.8-2.5	nds Ind side view (90° to 45° relative to the top plane of the box) Indexides Irregular objects coming soon.
Camera Position Top and Measurement objects Cuboid Range 0.8m to Measurement accuracy at Range (A)† 0.8-1.5 Measurement accuracy at Range (B)† 0.8-2.5	d side view (90° to 45° relative to the top plane of the box)
Measurement objects  Cuboic Range  0.8m t  Measurement accuracy at Range (A)†  Measurement accuracy at Range (B)†  0.8-2.8	ds. Irregular objects coming soon.
Range 0.8m t  Measurement accuracy at Range (A)† 0.8-1.5  Measurement accuracy at Range (B)† 0.8-2.5	· · · · · ·
Measurement accuracy at Range (A)† 0.8-1.5  Measurement accuracy at Range (B)† 0.8-2.5	o 4m**
Measurement accuracy at Range (B)† 0.8-2.	
, , , , , ,	5m range ± 5 mm
	5 m range ± 10 mm
Measurement accuracy at Range (C)† 0.8-4 i	m range (coming soon) ± 50 mm
Supported box sizes at range ‡ 5 × 5 ×	5 up to 90 × 80 × 50 (A)
(Depth x Width x Height) $10 \times 10^{-1}$	0 × 10 up to 100 × 120 × 100 (B)
30 × 3	0 × 30 up to 150 × 200 × 200 (C)
Supported Operating systems Windo	ws 10, Android/Linux coming soon
Supported Languages C, C++	



Intel and Intel RealSense are trademarks of Intel Corporation or its subsidiaries in the U.S. and/or other countries.

Other names and brands may be claimed as the property of others

<sup>\*</sup>Operational mode: Fixed/Static means both camera and object are not in motion, while Moving/Mobile means that either the camera or the object is moving during the measurement operation.

<sup>\*\*</sup>Distance between camera and floor. Minimum distance between the camera and object should be at least 0.7 m.

 $<sup>\ \ \, \</sup>dagger \, \text{Tested with wooden boxes on wooden floor with an 80\% reflectivity.} \, \text{Accuracy may vary depending on materials.}$ 

 $<sup>\</sup>ddagger$  Measured box should be positioned within 80% of the camera's field of view.